# ON CERTAIN SELF-SIMILAR MOTIONS OF GAS IN THE PRESENCE OF SHOCK AND DETONATION IN A MEDIUM OF VARYING DENSITY <br> (O NEKOTORYKH AVTOMODEL'NYKH DVIZHENIIAKH GAZA PRI UDARE I DETONATSII V SREDE S PEREMENNOI PLOTNOST'IU) 

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Self similar motions of gas subject to shock by a piston were analyzed by Sedov [l]. Equations derived there were applied not only to problems concerning pistons [ 2 to 4], but also to the mathematical analysis of detonation propagation in gases of variable density.

An analysis is made below of two-dimensional shock and detonation waves in gases the density of which varies in accordance with the law $\rho_{0}=a_{0} x_{0}{ }^{\omega}$ ( $x_{0}$ is the initial coordinate of a particle), and its unit mass heat content to $Q=Q_{0} x_{0}{ }^{2,3}$, in contrast to [5 and 6 ] where $Q=$ const.

We also assume that behind the detonation wave there is a piston moving with a velocity $\sim t^{\beta / 1^{-\beta}}$.

The presence of the additional parameter $\beta$ considerably complicates the fleld of integral curves as compared, for example, to the case considered in [5], due to the simultaneous inclusion in the analysis of a strong explosion, a piston, a solution of a dipolar type, a detonation from the free boundary and of a short shock [7].

The behavior of integral curves is analyzed.
Cases are noted in which the detonation from the free boundary must nevertheless be supercompressed, while in the presence of shock it must correspond to the Jouguet point. An exact solution is found for the problem of a short shock in a medium of varying density for a number of values of $w$ dependent on $\gamma$, thus generalizing the solution of the known case of $\gamma=1.4$, $p_{0}=$ const.

1. The motion of a gas behind a strong detonation wave (or shock wave, when $Q_{0}=0$ ) are defined by the following equations of hydrodynamics

$$
\begin{equation*}
\frac{\partial u}{\partial t}=-\frac{1}{\rho_{0}}-\frac{\partial p}{\partial x_{0}}, \quad \frac{\partial u}{\partial x_{0}}=\frac{\partial}{\partial t} \xrightarrow[\rho]{\rho}, \quad p \rho^{-\gamma}=p_{*}\left(x_{0}\right) \rho_{*}^{-\gamma}\left(x_{0}\right) \tag{1.1}
\end{equation*}
$$

In the following text the subscript, will always be used for denoting* parameter values at the wave front. Boundary conditions for.(1.i) are determined by the conservation laws at the front $x_{*}(t)$

$$
\begin{gather*}
\rho_{0} D=\rho_{*}\left(D-u_{*}\right), \quad p_{*}=\rho_{0} D u_{*}  \tag{1.2}\\
\frac{\left(D-u_{*}\right)^{2}}{2}+\frac{\gamma p_{*}}{\rho_{*}(\gamma-1)}=\frac{D^{2}}{2}+Q_{0} x_{*}^{2 \cdot 3}, \quad D=\frac{d x_{*}}{d t}
\end{gather*}
$$

aru by the equality of gas and piston velocities $u(0, t)=v_{0} x_{*}$, or in the case of expansion into vacuum, by the pressure being equal to zero, $p(0, t)=0$.

We seek a solution in the form of

$$
\begin{array}{ccc}
u=u_{*} v(x), \quad p=p_{*} f(x), & \rho=\rho_{*} q(x), \quad x=x_{0} / x_{*} \\
u_{*}=u_{0} x_{*}^{\beta}, \quad p_{*}=a_{0} D_{0} u_{0} x_{*}^{2 \beta+\omega}, \quad D=D_{0} x_{*}^{\beta}, \quad \rho_{*}=\frac{a_{0} D_{0}}{D_{0}-u_{0}} x_{*}^{\omega} \tag{1.3}
\end{array}
$$

Boundary conditions (1.2) are satisfied when constants $D_{0}$, $\psi_{0}$ and $Q_{0}$ are related by Expressions

$$
\begin{equation*}
u_{0}^{2}\left(\frac{2 \gamma}{\gamma-1}-\lambda\right)=2 \lambda Q_{0}, \quad \lambda=\frac{\gamma u_{0}}{D_{0}-u_{0}} \tag{1.4}
\end{equation*}
$$

In the physical sense $\lambda$ represents the squared ratio of the velocity of sound to the mass flow rate behind the wave front in a coordinate system in which the front is at rest.

The value of parameter $\theta_{0}$ is assumed to be specified, while $\lambda$ is defined as the elgen number of the boundary value problem with $x_{0}=0$ and $x_{0}=x_{*}$, 1.e. is dependent on the piston velocity.

Substituting (1.3) into (1.1) we find the system of equations of dimensionless functions

$$
\begin{gather*}
x^{-\omega} \frac{d f}{d x}-x \frac{d v}{d x}+\beta v=0, \quad \lambda \frac{d v}{d x}+\gamma x \frac{d}{d x} x^{\omega} q^{-1}=0  \tag{1.5}\\
f=q^{\gamma} x^{\mu}, \quad \mu=2 \beta+\omega-\gamma \omega, \quad f(1)=1, \quad v(1)=1
\end{gather*}
$$

Equations (1.5) allow a similarity set. After the change of variables

$$
\begin{equation*}
f^{\gamma+1}=\left(\frac{z}{\lambda}\right)^{\gamma} x^{\delta}, \quad\left(\frac{v}{w}\right)^{\gamma+1}=\left(\frac{z}{\lambda}\right)^{\gamma} x^{2 \beta+\gamma-1} \quad(\delta=\omega(\gamma+1)+2 \gamma+2 \beta) \tag{1.6}
\end{equation*}
$$

they become

$$
\begin{equation*}
(1-z) \frac{d z}{d \eta}=\varphi(z, w), \quad(1-z) \frac{d w}{d \eta}=\varphi(z, w), \quad \eta=\ln x, \quad z(1)=1, \quad w(1)=1 \tag{1.7}
\end{equation*}
$$

Eliminating the variable $\eta$, we obtain

$$
\begin{gather*}
\frac{d z}{d w}=\frac{\varphi}{\psi}, \quad \varphi=2 z\left\{\beta-1+[\delta+(\gamma+1) \beta w] \frac{z}{2 \gamma}\right\} \\
\dot{\psi}=\omega+2 \beta+(1-\beta) w-(\omega+1) w z-\beta w^{2} z,\left.\quad z\right|_{w=1}=\lambda \tag{1.8}
\end{gather*}
$$

These expressions contain four parameters $\gamma, B, \omega$ and $\lambda$ which determine the solution character.

We shall limit the area of variation of these parameters for physical reasons.

We shall consider detonation and shock waves which satisfy the necessary stability conditions $c_{*}+u_{*} \geqslant D, c_{*}{ }^{3} \rho_{*}=\Upsilon p_{*}$, when small perturbations are catching up with a strong discontinuity front. It follows from (1.4) that this condition is fulfilled if $\lambda \geq 1$. On the other hand, we have $\lambda \leq 2 y /(\gamma-1)$, because $0_{0} \geq 0$. It is known from thermodynamies that $c_{p}-c_{v}>0$, consequently $y>1$.

The condition for the mass of matter behind the wave front to be finite stipulates $\omega>-1$. We note that when $\beta \geq 1$, a shock wave cannot detach itself from the coordinate origin, even after an infinitely long period of time. Consequently, there exists a self-similar solution when $\beta<1$. In the wave front proximity there is an area $x_{1}<x \leq 1$, where $u>0$, because $D>0$. With this, the total mass of gas either moves in the direction of $x>0$, or $u\left(x_{1}\right)=0$. The impulse of the mass of gas moving in the direction of $x>0$ is proportional to $x^{\omega+1+\beta}$ and, because $p(x, t) \geq 0$, it does not diminish with time (see [8], $p .605$ ), therefore, $\omega+B+1 \geq 0$. It will be shown in section 3 that, if in the latter expression the equality sign is valid, there will be no continuous solutions in the whole area defined by $0 \leq x \leq 1$. We shall therefore assume that $\omega+\beta+1>0$. Continuous solutions are also limited by variations of parameter $\beta \geq \beta_{0}<$ $<-0.5(\omega+1)$ up to the value of $\beta_{0}$ corresponding to a short shock.

The area of variation of $z$, and $\omega$ is also limited. As pressure is a nonnegative parameter, we have $z \geq 0$. Simplifying Equation (1.7) in the neighborhood of the wave front, where $w \rightarrow 1$ and $0<d w / d \eta=w+p+1+0(w-1)$, we come to the conclusion that the value of $w \leq 1$ must decrease with decreasing $x$.

We write down the derived limitations

$$
\begin{gather*}
z \geqslant 0, w \leqslant 1, \gamma>1, \omega+1>0 \\
\omega+1+\beta>0, \beta<1,1 \leqslant \lambda \leqslant 2 \gamma /(\gamma-1) \tag{1.9}
\end{gather*}
$$

2. We shall plot the field of integral curves of Equation (1.8). The isocilnes of zeros $z_{0}(w)$, infinities $\dot{\boldsymbol{z}}_{\infty}(w)$, and the particular solution $z \equiv 0$, all intersect at the following singular points

$$
A\left(w_{1}=\frac{\omega+2 \beta}{\beta-1}, \quad z_{1}=0\right)
$$

$$
B\left(w_{2}=-2-\frac{\omega}{\beta}, \quad z_{2}=1\right), \quad C\left(w_{3}=\frac{\omega(\gamma-1)+2 \gamma+2 \beta}{(\gamma-1)(1-\beta)}, \quad z_{3}=\frac{2 \gamma(1-\beta)}{w_{3}(2 \beta+\gamma-1)}\right)
$$

Point $A$ is always a "saddle" point. For the isocline of infinities $\boldsymbol{z}_{\infty}=\boldsymbol{z}_{\infty}(w)$, as well as for the slope of the particular solution $z_{1}(w)$ at point ${ }^{\infty} A$ we have

$$
\frac{d z_{\infty}}{d w}=\frac{(1-\beta)^{3}}{(2 \beta-1)(\omega+2 \beta)(\omega+1+\beta)}, \quad \frac{d z}{d w}=\frac{1-\beta+2(1-3)}{(2 \beta-1)(\omega+2(\beta)(w+1+\beta)}
$$

In the neighborhood of $B$, Equation (1.8) becomes

$$
\begin{equation*}
\frac{d y}{d r}=\frac{a r+b y}{c r+e y}, \quad y=z-z_{2}, \quad r=w-w_{2}, \quad \gamma a=(\gamma+1) \beta z_{2}{ }^{2} \tag{2.1}
\end{equation*}
$$

$$
b=2(1-\beta), \quad c=1-\beta-(\omega+1) z_{2}-2 \beta w_{2} z_{2}, \quad e=-w_{2}\left(\omega+1+\beta w_{2}\right)
$$

The singular point $B$ will be a "saddle" point when $a_{e}-b_{c}>0$; a nodal point when inequality $0<\ell<(b+c)^{2}$ is fulfilled with $\ell=4\left(a e-b_{0}\right)+(b+c)^{2}$, and a focal point when $\ell<0$.

The slope of the zero and infinity isocilnes at point $B$ will be

$$
\begin{equation*}
\left.\frac{d z_{0}}{d w}\right|_{2}=\frac{(\gamma+1) \beta}{2 \gamma(\beta-1)},\left.\quad \frac{d z_{\infty}}{d w}\right|_{2}=\frac{(\omega+3 \beta) \beta}{(2 \beta-1)(\omega+2 \beta)} \tag{2.2}
\end{equation*}
$$

and the slape of singular solutions are found from (2.1), if $y=K r$ is assumed.

In the neighborhood of $C$ Equation (1.8) takes the form of (2.1), if in the latter we substitute $w_{3}$ and $z_{3}$ for $w_{2}$ and $z_{2}$, respectively. For analyzing this problem at points. $B$ and $C$ it is conveneient to express the term ( $a e-b c$ ) in the form

$$
\begin{equation*}
\gamma(a e-b c)_{2}=(\gamma-1) \beta(1-\beta)\left(w_{2}-w_{3}\right) \tag{2.3}
\end{equation*}
$$

$$
(2 \beta+\gamma-1)(a e-b c)_{3}=2(\gamma-1) \beta(1-\beta)^{2} w_{3}\left(w_{3}-w_{2}\right)
$$

The analysis, with inequalities (1.9) taken into account, is reduced to the consideration of ten characteristic cases shown in Fig.l, where curves of identical physical meaning are denoted by the same letters. Only the isoclines essential for the analysis of this problem have been shown (by dotted lines) in Fig.1. Possible directions of solutions are indicated by arrows. Points on segment $K L$ correspond to conditions at the wave front, with points $K$ (the Jouguet point), $L(Q=0)$, and $K_{1}$ (supercompressed detonation) defined by coordinates

$$
K(w=1: z=1), \quad L\left(w=1, z=\frac{2 \gamma}{\gamma-1}\right), \quad K_{1}(w=1, z=\lambda>1)
$$

The asymptotic behavior of curves between $L Q$ and $K N$ (or $K_{1} N$ ) for $z \rightarrow \infty, w \rightarrow 0$ is found from (1.8)

$$
\begin{gather*}
z \sim|w|^{-\alpha} \sim x^{-\alpha(w+1)}, \gamma(\omega+1) \alpha=\omega(\gamma+1)+2 \gamma+2 \beta  \tag{2.4}\\
f(0) \rightarrow \mathrm{const}, \quad v(0) \rightarrow \mathrm{const}
\end{gather*}
$$

These curves, therefore, correspond to a flow pattern in which the piston moves in the direction of $x>0$, or $x<0$, depending on whether it approaches the $z$-axis from the left, or right, respectively.


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Curve LQ corresponds to the compression of the nondetonating gas. The asymptotic behavior of curves between $D R$ is also defined by (2.4), with $v(0)<0$, The asymptotic behavior of curves $R R$ and $C R$ is determined by

$$
\begin{align*}
z=\frac{K_{1}}{w} \sim x^{-\alpha(\omega+1)}, & (\omega+\gamma+1-2 \beta) K_{1}=-\omega-2 \beta \\
& f \rightarrow \text { const, } \quad  \tag{2.5}\\
& v \sim x^{(\omega+1)(\alpha-1)} \rightarrow 0
\end{align*}
$$

which means that these correspond to a detonation from the closed end, or to a strong explosion.

When $z \rightarrow \infty, \quad w \rightarrow w_{4}=-(w+1) / B$, the behavior or curves $B D$, or $C D$ is defined by

$$
\begin{gather*}
z=\frac{K_{2}}{w-w_{4}} \sim x^{-\varepsilon}, \quad \gamma \varepsilon=2 \beta+\gamma-1, \quad \beta(1+\varepsilon) K_{2}=(\omega+1)(1-2 \beta) \\
 \tag{2.6}\\
f \sim x^{\omega+1} \rightarrow 0, v \rightarrow \mathrm{const}<0
\end{gather*}
$$

and correspond to a detonation from the free boundary.
The asymptotic behavior of $K F$ or $K_{1} F$ for $w \rightarrow-\infty$ has the from

$$
\begin{equation*}
z=\frac{\gamma(1-\beta)}{\beta w} \sim x^{(1-\beta)(\gamma-1)}, f \sim x^{q} \rightarrow 0, v \sim-x^{\beta}, q=\omega+\beta+1+(\gamma-1)(1-\beta), \beta<0 \tag{2.7}
\end{equation*}
$$ and corresponds to a discharge into vacuum.

Integral curves corresponding to continuous solutions cannot intersect line $=1$ at any point $w=w_{5}$, except where $w_{5}=w_{3}$. We find from (1.7) that in the neighborhood of $z=1, w=w_{5}$, we have $d\left(w-w_{3}\right) 3 / d n>0$. This means that, once line $:=1$ had been crossed, $x$ begins to grow again, and $x \rightarrow \infty$ with $w \rightarrow-\infty$, which contradicts physical notions.

Fig.I shows the field of integral curves for all possible cases of variation of parameters $\gamma, \omega, \beta$ and $\lambda$ which satisfy inequalities (1.9)

Case 1. $0.5 \leq \beta<1, \quad \ell_{2}=(\omega+5 \beta-2)^{2}-4(1+1 / y)(2 \beta-1)(\omega+2 \beta) \geq 0$. In accordance with $(2.3),\left(a e-b_{c}\right)_{2}<0$, and as also $t_{2} \geq 0$, therefore, $B$ is the nodal point. The solution emanating from point $B$ is below the isocline of zeros. The form of Equation (i.7) in the neighborhood of point $B$ is

$$
\begin{align*}
k \frac{d w}{d \eta} & =A_{1}+k A_{2}, & \left(\frac{d z_{\infty}}{d w}\right)_{2} & =-\frac{A_{1}}{A_{2}}, \quad k=\left(\frac{d z}{d w}\right)_{2}  \tag{2.8}\\
A_{1} & =\omega+\beta+2 \beta w_{2}, & A_{2} & =\left(\omega+1+\beta w_{2}\right) w_{2}
\end{align*}
$$

Because $k<d z_{\infty} / d w$, it follows from (2.8) that $d w / d \eta<0$, which means that the solution can be extended in these directions. It will be seen from Fig.l that the Jouguet point corresponds not only to detonation from the open end, but also to the case of the piston moving with velocity greater than a certain given value $v(0) \leq v_{1}>0$. The asymptotic behavior of curve $K W$ is in accordance with (2.4).

Case 2. $0.5<6<1, \ell_{2}<0 . B$ is a focal point. When approaching this point, the curves intersect line $z=1$ at points $w \neq w_{2}$, while $x$ becomes nonsingle-valued. Continuous solutions, can, therefore, exist only when the velocity of the compressing piston is $v(0)>v_{0}>0$.

Case 3. $0<\beta<0.5, \omega+2 \beta \geq 0 . B$ is a nodal point, because of $w_{2}-w_{3}<0$, while the minimum value of $\ell_{2}=8_{B}(1-2 \beta)>0$ (for $y \rightarrow 1$ and $\omega=3 \beta-2$ ).

Case 4. $0<\beta<0.5,-0 \leq w+2 \beta<0,(2 \beta+y-1) \delta=2 y \beta(1-\beta)$. $\quad$. $B$ (a nodal point) moves into the right-hand half-plane. The Jouguet point corresponds to detonation from the free boundary (2.6), as well as to detonation with piston velocity $v(0) \leq v_{2} \geq 0$.

Case 5. $0<\beta<0.5, \omega+2 \beta<-8$. Points $B$ and $C$ exchange their
respective places. In accordance with (2.3), C is not a "saddle" point, and neither is it a focal point in view of

$$
\begin{aligned}
& { }_{3}:-\left(a_{1}+b_{1}+c_{1}\right)^{2}-4(1+1 / \gamma) a_{1} b_{1}>\left(a_{1}+2 b_{1}\right)^{2}-8 a_{1} b_{1}>0 \\
& y_{1}=1-\beta>a_{1}=3 z_{3} w_{3}>0, \quad c_{1}>b_{1}=z_{3}\left(\omega+1+\beta w_{3}\right)>0
\end{aligned}
$$

Therefore, $C$ is a nodal point. Possible continuous solutions are bounded by curve $K_{1} \mathcal{L}$ which. corresponds to supercompressed detonation from the open end (2.6).

Case $6 .{ }_{y}=0, \omega>0$. Point $B$ has receded into infinity, and $C$ is a "saddle" point. The particular solution $z \equiv \lambda_{0},[(\gamma+1) \omega+2 \gamma] \lambda_{0}=2 \gamma$ is unstable, since $\lambda_{0}<1$. The asymptotic behavior of curves $K M$ is defined by

$$
\begin{equation*}
z \rightarrow \lambda_{0}, \quad w \rightarrow-\infty, \quad f \sim x^{\omega+2 \gamma i(\gamma+1)} \rightarrow 0, \quad v \rightarrow \text { const }<0 \tag{2.9}
\end{equation*}
$$

This case represents detonation from the open end.
Case 7. $B=0,-1<\omega \leq 0 . C$ is a nodal point. The particular solution is $z \equiv \lambda_{0} \geq 1$, and the detonation, even from the open end $\left(K_{1} M\right)$, is supercompressed.

Case 8. $\omega+2 \beta \geq-\beta>0$. The Jouguet point corresponds to detonation from the free boundary, or to compression by piston with $u(0, t)>0$. The two singular points $B$ and $C$ are located to the right of ilne $K I$, and it follows from (2.3) that:
a) if $\omega+2 \beta \geq-\delta$ and $2 \beta+\gamma-\frac{1}{\mu}>0$, then $w_{2} \geq w_{3}>1, \quad B$ is a nodal point, and $C$ a "saddle" point. If the equality sign applies, these two points coincide.
b) if $-\beta<\omega+2 \beta<-\delta, 2 \beta+{ }_{\mu} Y-1>0$, then $w_{3}>w_{2} \geq 1$, and $C$ is a nodal point, while $B$ a "saddle" point.
c) if $\omega+2 \beta \geq-\beta, \quad 2 \beta+\gamma-1 \leq 0$, then $w_{2} \geq 1, \quad B$ is a "saddle" point, and $C$ moves into the íower half-plane.

Case $9.0 \leq \omega+2 \beta<-B>0$. $B$ is a "saddle" point ( $0<w_{2}<1$ ). The separation line from point $B$ runs above $z=1$ for $w=1$. Continuous solutions are, therefore, above the Jouguet point. Detonation is supercompressed even from the free boundary $\left(K_{1} B F\right)$. In accordance with (2.8), solutions from $B$ may only be extended in the directions indicated by arrows. $C\left(w_{3}>1\right)$ is a nodal point when $2 \beta+\gamma-1>0$. If $2 \beta+\gamma-1 \leq 0$, then $C$ moves into the lower half-plane.

Case 10. $\omega^{\omega+2 \beta<0, ~} B<0 . B$ is a "saddle" point, $C$ a nodal point, $w_{2}<0$, $w_{3}>1$. With $2 \beta+\gamma-1>0, z_{3}>0$, when $2 \beta+\gamma-1 \leq 0$, point $C$ moves into the lower half-plane.

Depending on the law of variation of the total gas energy, which is proportional to $x_{*}^{\nu}$, with $\nu=\omega+2 \beta+1$, we obtain the following characteristic cases:
a) With $\nu>0$, a detonation (supercompressed) from point $K_{1}$ is possible with a free boundary $K_{1} B F$ and a piston moving in the negative direction of axis $x K_{1} B N$.
b) When $\nu=0$, curve $L Q$, which now coincides $w i t h$ the separation line $C R$, corresponds to a strong explosion. Curves below line LQ correspond to detonation in the presence of a piston which for $t \rightarrow 0$ absorbs a logarithmically infinite part of the detonating mixture energy, while the total energy of the gas remains constant. A discharge into vacuum $K_{1} B F$ is also possible with an infinite energy (2.8), but in contrast to [7] this takes place when $0_{0}>0$.
c) With $v<0$, curve $L Q$ runs below the separation line $C R$. The piston imparts to the gas an infinitely great energy by shock $t=0$ ), and immediately begins to take it away by reversing its motion. At any finite instant of time the energy is also finite, even when $Q_{0}>0$ (curves between $L Q$ and $K_{1} B N$ ). These solutions bring to mind those of the dipole type for nonlinear thermal conductivity [9].
a) When $\nu=w^{\circ}<0$, point $L$ descends lower and lower with decreasing $v$, finally reaching point $K_{1}$ of iine $C R$. In this case there exists a solution of either the dipole type (in the presence of a piston $u(0, t)<0)$, or of the impulse type $K_{1} D F$ when the gas energy is infinitely great.
e) With $v<v_{0}$, there are no continuous solutions in the whole area defined by $0 \leq x \leq 1$, since in this case curves $C P$ intersect Ilne $\boldsymbol{z}=1$ at points $w \neq w_{2}$. We may, however, visualize a short shock with energy absorption at the front $\lambda>2 y /(y-1)$; With $8>1$ the self-similar solutions may be considered as a limit for the non-self-similar solutions (if, for example, $0=Q_{*}+Q_{0} x_{0}{ }^{2} \mathrm{~B}$ ). It appears that in this case continuous solutions are only possibie, If the piston velocity $i(0, t) \geqslant v>0$ is greater than a certain specified value.
3. Particular solutions of Equations (1., ) may be derived, for example, In cases of constant wave velocity, existence of energy and impulse integrals, and when the pressure s a power function of $x$.

Equation (1.8) becomes inear for $s=0$, and is expressed in terms of $z$ by a quadratic form, while the dependence of $z$ on $x$, derived from (1.7), is

$$
\begin{align*}
& w \sqrt{\frac{z}{\lambda}}\left|\frac{z-\lambda_{0}}{\lambda-\lambda_{0}}\right|^{x}=\frac{\omega \lambda_{0}}{2 \lambda} \int_{\lambda}^{z} \sqrt{\frac{\lambda}{z}}\left|\frac{z-\lambda_{0}}{\lambda-\lambda_{0}}\right|^{x} \frac{d z}{z-\lambda_{*}}+1  \tag{3.1}\\
& z x=\lambda\left|\frac{z-\lambda_{0}}{\lambda-\lambda_{0}}\right|^{1-\lambda_{0}}, \quad \lambda_{0}=\frac{2 \gamma}{2 \gamma+\omega(\gamma+1)}, \quad x=\frac{1}{2}(w+1) \lambda_{0}-\frac{1}{2}
\end{align*}
$$

The integral curves $z=z(w)$ of Equation (3.1) are illustrated in Fig. I by cases 6 and 7 . With $\omega \leq 0$, there exists a further particular solution which identically satisfies (1.8), while the definite integral of (1.7) is of the form

$$
\begin{align*}
& z \equiv \lambda_{*}, \quad x=\left|\frac{\omega+w\left(1-\alpha \lambda_{0}\right)}{\alpha\left(1-\lambda_{0}\right)}\right|^{\frac{1-\lambda_{0}}{1-\alpha \lambda_{\theta}}}, \quad \alpha=\omega+1  \tag{3.2}\\
& f=x^{\frac{\alpha \gamma \lambda_{*}}{\gamma+1}}, \quad v=\frac{2 \gamma}{(\gamma-1) \lambda_{0}} x^{\frac{\gamma-1}{\gamma+1}}-\frac{\gamma+1}{\gamma-1} \alpha
\end{align*}
$$

This solution corresponds to supercompressed detonation from the open end (2.9). If $w=0$, then Equation (1.5) has a further solution $v=$ const, $f$. const which may be matched to $(3,2)$. This case was the subject of detalled studies in [I, 10 and 11].

With $w+2 \theta+1=0$, and the piston energy taken into account, the expression of the energy integral [5] which, incidentally, also exists in the case of dipole type of flows, is as follows:

$$
\begin{gather*}
\left((x)^{1-1 / \gamma}+\frac{\gamma-1}{2 \gamma} \lambda v^{\eta} x^{\omega+1}-\frac{\gamma-1}{\gamma} \lambda v f+\frac{\gamma-1}{\gamma} \lambda v_{0} f_{0}=0\right.  \tag{3.3}\\
u(0, t)=u_{0} v_{0} x_{*} \quad p(0, t)=a_{0} D_{0} u_{0} f_{0} x_{*}^{\omega+2 \beta}
\end{gather*}
$$

By virtue of conditions at the wave front we have $2 v_{0} f_{0}=1-2 \gamma /(y-1) \lambda$. With known piston velocity $u(0, t)$ and $Q_{0}$ we integrate the second of Equations (1.5) by using (3.3), and obtain a single-valued solution from which the value of the constant energy of gas is derived.

A particular solution may also be obtained by assuming that the pressure is a power function of the coordinate. It follows from (1.5) that function $f$ satisfies Equation

$$
\begin{align*}
\frac{d}{d x}\left[x^{-\omega} \frac{d f}{d x}+\frac{\gamma}{\lambda} x^{2} \frac{d}{d x}\left(x^{\omega+2 \beta} f-1\right)^{1 / \gamma}\right] & =\frac{\gamma \beta}{\lambda} x \frac{d}{d x}\left(x^{2 \beta+\omega} j-1\right)^{y / \gamma}  \tag{3.4}\\
f(1)=1,\left.\quad(1-\lambda) \frac{d f}{d x}\right|_{1} & =2 \beta+\lambda \beta+\omega
\end{align*}
$$

If $j=x^{\mu}$, then, in accordance with assumptions made in [12], it follows from (3.4) that

$$
\begin{gather*}
(\omega+2 \beta-\mu)(\gamma 3+\mu-\gamma-\omega-2 \beta) x^{(\omega+2-\mu) \gamma}=\mu(\mu-\omega-1) x^{\mu-\omega-2}  \tag{3.5}\\
\lambda \mu+\lambda \beta+\omega+2 \beta=\mu \tag{3.6}
\end{gather*}
$$

Equation (3.5) may be satisfied either by equating to zero coefficients at the various powers of $x$, or by stipulating the equality of exponents and equating to zero the sum of coefficients. Condition $\omega>-1$, together with Equation (3.6) can only be satisfied by the first procedure, therefore

$$
\begin{gather*}
f=x^{1 \mu}, \quad v=\left(1+\frac{\mu}{\beta}\right) x^{\beta}-\frac{\mu}{\beta}, \quad \mu=\omega+1, \quad \beta=\frac{1-\gamma}{2-\gamma} \\
\omega=\frac{(3-2 \gamma) \lambda-\gamma}{\lambda(\gamma-2)}, \quad 1<\gamma<2 \tag{3.7}
\end{gather*}
$$

With $\lambda=2 \gamma /(\gamma-1)$ we have an exact solution of the problem of impulse in a variable density medium, which is a generalized solution of the known case [13], when $\omega=0$.

When $1 \leq \lambda<2 \gamma /(\gamma-1)$, then (3.7) defines the motion of a gas in the presence of detonation.

It can be ascertained with the use of (1.6) that with $x_{2}^{\beta}=\lambda$ this solution passes through point $B, F 1 g .1$ (Case 10).

When $\omega+\beta+1=0$; then the second of Equations (1.7) yields the integral (of impulse [5]), $w \equiv 1$, while the first of Equations (1.7) is integrated in the quadratic form

$$
x^{2(1-\beta)} z=\lambda\left|\frac{z+b_{0}}{\lambda+b_{0}}\right|^{1+b_{0}}, \quad b_{0}=\frac{2 \gamma(\beta-1)}{2 \beta-\gamma-1}
$$

This solution corresponds to curves $C P$ in Fig.l and cannot be continuous for all $0 \leq x \leq 1$. In the discontinuity area, such a solution may be arrived at by, for example, artificially bleeding the gas into a container [12] which moves in accordance with a stipulated law.

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